

```
/*
 * File: 8x8_matrix_vinyl.c
 * Author: Phil Glazzard
 *
 * Created on 16 August 2016, 17:59
 */
/* This design drives five 8x8 common cathode LED matrices
 * via MAX7219 constant current drivers using SPI on the
 * PIC 16f690 microcontroller
 */
/* PIC pin assignment
 * SDO pin 9 (serial data out) drives DIN of MAX7219
 * SCK pin 11 (serial clock) drives CLK of MAX7219
 * RC6 pin 8 (load) drives CS of MAX7219
 */

#include <xc.h>

// CONFIG

#pragma config FOSC = INTRCIO // Oscillator Selection bits
#pragma config WDTE = OFF // Watchdog Timer Enable bit
#pragma config PWRTE = OFF // Power-up Timer Enable bit (PWRT disabled)
#pragma config MCLRE = ON // MCLR Pin Function Select bit
#pragma config CP = OFF // Code Protection bit
#pragma config CPD = OFF // Data Code Protection bit
#pragma config BOREN = OFF // Brown-out Reset Selection bits (BOR disabled)
#pragma config IESO = OFF // Internal External Switchover bit
#pragma config FCMEN = OFF // Fail-Safe Clock Monitor Enabled bit

#define _XTAL_FREQ 4000000 // 4MHz internal clock
#define SDO PORTCbits.RC7 // data in 16f690 pin 9
```

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#define LOAD PORTCbits.RC6 // load 16f690 pin 8

#define SCK PORTBbits.RB6 // clock 16f690 pin 11

//*****CONSTANTS*****

#define normal_operation_addr 0x0C //normal operation mode hi byte
#define normal_operation_data 0x01 //normal operation mode lo byte

#define decode_off_addr 0x09 // no BCD decoding needed hi byte
#define decode_off_data 0x00 // no BCD decoding needed lo byte

#define scan_limit_addr 0x0B // display 8 columns of leds hi byte
#define scan_limit_data 0x07 // display 8 columns of leds lo byte

#define display_intensity_addr 0x0A // minimum display intensity hi byte
#define display_intensity_data 0x00 // minimum display intensity lo byte

#define no_op_addr 0x00 // No operation address
#define no_op_data 0x00 // No operation data

/*****STRING MESSAGE TO DISPLAY*****/

#define MESS_CHAR 41 // number of characters in message array (including spaces and symbols)+1
FOR NULL CHARACTER

//const char message[37] = "vinyl available at rear of store # ^ "; // string of characters stored in EEPROM
//const char message[MESS_CHAR] = "huge range of vinyl albums in store # ^ ";

const char message[] =
{
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x00,0x7F,0x7F,0x04,0x04,0x7C,0x78,0x00, // h
0x3c,0x7c,0x40,0x40,0x7c,0x7c,0x00,0x00, // u
0x98,0xBC,0xA4,0xA4,0xFC,0x7C,0x00,0x00, // g
0x38,0x7C,0x54,0x54,0x5C,0x18,0x00,0x00, // e

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0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x44,0x7c,0x78,0x4c,0x04,0x1c,0x18,0x00, // r
0x00,0x74,0x54,0x54,0x7c,0x78,0x00,0x00, // a
0x7C,0x7C,0x04,0x04,0x7C,0x78,0x00,0x00, // n
0x98,0xBC,0xA4,0xA4,0xFC,0x7C,0x00,0x00, // g
0x38,0x7C,0x54,0x54,0x5C,0x18,0x00,0x00, // e
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x38,0x7C,0x44,0x44,0x7C,0x38,0x00,0x00, // o
0x48,0x7E,0x7F,0x49,0x03,0x02,0x00,0x00, // f
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x1c,0x3c,0x60,0x60,0x3c,0x1c,0x00,0x00, // v
0x00,0x44,0x7D,0x7D,0x40,0x00,0x00,0x00, // i
0x7C,0x7C,0x04,0x04,0x7C,0x78,0x00,0x00, // n
0x9c,0xbc,0xa0,0xa0,0xfc,0x7c,0x00,0x00, // y
0x00,0x41,0x7F,0x7F,0x40,0x00,0x00,0x00, // l
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x00,0x74,0x54,0x54,0x7c,0x78,0x00,0x00, // a
0x00,0x41,0x7F,0x7F,0x40,0x00,0x00,0x00, // l
0x00,0x7f,0x7f,0x48,0x48,0x78,0x30,0x00, // b
0x3c,0x7c,0x40,0x40,0x7c,0x7c,0x00,0x00, // u
0x7C,0x7C,0x18,0x38,0x1C,0x7C,0x78,0x00, // m
0x48,0x5c,0x54,0x54,0x74,0x24,0x00,0x00, // s
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x00,0x44,0x7D,0x7D,0x40,0x00,0x00,0x00, // i
0x7C,0x7C,0x04,0x04,0x7C,0x78,0x00,0x00, // n
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x48,0x5c,0x54,0x54,0x74,0x24,0x00,0x00, // s
0x00,0x04,0x3e,0x7f,0x44,0x24,0x00,0x00, // t
0x38,0x7C,0x44,0x44,0x7C,0x38,0x00,0x00, // o

```
0x44,0x7c,0x78,0x4c,0x04,0x1c,0x18,0x00, // r
0x38,0x7c,0x54,0x54,0x5c,0x18,0x00,0x00, // e
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x7e,0x81,0x95,0xa1,0xa1,0x95,0x81,0x7e, //#smiley
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0xc0,0xff,0x7f,0x05,0x05,0x65,0x7f,0x3f, //^note
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space
0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, //space

/*****ASCII to 8x8 bit map LUT*****/

#define ROWS 30

#define COLS 9

const char alphabet[ROWS][COLS] = // 30 rows by 9 columns

{
    {'a', 0x00,0x74,0x54,0x54,0x7c,0x78,0x00,0x00},
    {'b', 0x00,0x7f,0x7f,0x48,0x48,0x78,0x30,0x00},
    {'c', 0x38,0x7c,0x44,0x44,0x6c,0x28,0x00,0x00},
    {'d', 0x30,0x78,0x48,0x48,0x7f,0x7f,0x00,0x00},
    {'e', 0x38,0x7c,0x54,0x54,0x5c,0x18,0x00,0x00},
    {'f', 0x48,0x7e,0x7f,0x49,0x03,0x02,0x00,0x00},
    {'g', 0x98,0xbc,0xa4,0xa4,0xfc,0x7c,0x00,0x00},
    {'h', 0x00,0x7f,0x7f,0x04,0x04,0x7c,0x78,0x00},
    {'i', 0x00,0x44,0x7d,0x7d,0x40,0x00,0x00,0x00},
    {'j', 0x00,0x40,0xc0,0x80,0xfd,0x70,0x00,0x00},
    {'k', 0x00,0x7f,0x7f,0x10,0x38,0x6c,0x44,0x00},
    {'l', 0x00,0x41,0x7f,0x7f,0x40,0x00,0x00,0x00},
```

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{'m', 0x7C,0x7C,0x18,0x38,0x1C,0x7C,0x78,0x00},
{'n', 0x7C,0x7C,0x04,0x04,0x7C,0x78,0x00,0x00},
{'o', 0x38,0x7C,0x44,0x44,0x7C,0x38,0x00,0x00},
{'p', 0x00,0xFC,0xFC,0x24,0x24,0x3C,0x18,0x00},
{'q', 0x18,0x3c,0x24,0x24,0xfc,0xfc,0x00,0x00},
{'r', 0x44,0x7c,0x78,0x4c,0x04,0x1c,0x18,0x00},
{'s', 0x48,0x5c,0x54,0x54,0x74,0x24,0x00,0x00},
{'t', 0x00,0x04,0x3e,0x7f,0x44,0x24,0x00,0x00},
{'u', 0x3c,0x7c,0x40,0x40,0x7c,0x7c,0x00,0x00},
{'v', 0x1c,0x3c,0x60,0x60,0x3c,0x1c,0x00,0x00},
{'w', 0x3c,0x7c,0x70,0x38,0x70,0x7c,0x3c,0x00},
{'x', 0x44,0x6c,0x38,0x10,0x38,0x6c,0x44,0x00},
{'y', 0x9c,0xbc,0xa0,0xa0,0xfc,0x7c,0x00,0x00},
{'z', 0x4c,0x64,0x74,0x5c,0x4c,0x64,0x00,0x00},
{'.', 0x00,0x00,0x60,0x60,0x00,0x00,0x00,0x00},
{'#', 0x7e,0x81,0x95,0xb1,0xb1,0x95,0x81,0x7e}, //smiley
{' ', 0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00}, // space
{'^', 0x08,0x08,0x08,0x2a,0x3e,0x1c,0x08,0x00} //^arrow
};

void init_ports()
{
//*****ANSEL&COMPARATORS SETUP*****
ANSEL = 0x00;      // AD module off

ANSELH = 0x00;

CM1CON0 = 0x00;    // Comparator module off

CM2CON0 = 0x00;

//*****TRISbits SETUP*****

TRISBbits.TRISB4 = 1; // disable SDI facility as we don't want to

// receive data back from the slave

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```

TRISCbits.TRISC7 = 0; // OUTPUT to Data in

TRISCbits.TRISC6 = 0; // OUTPUT to Load

TRISBbits.TRISB6 = 0; // OUTPUT to Clock

TRISBbits.TRISB5 = 0; // OUTPUT to diagnostic led

PORTBbits.RB5 = 0;

/*****/

}

void init_spi(void)

{

/*****SSPCONbits*****/

SSPCONbits.SSPM = 0000; // SPI Master mode, clock = Fosc/4 = 1MHz

SSPCONbits.CKP = 0; // idle state for clock is low

SSPCONbits.SSPEN = 1; // enables seial port and configures SCK, SDO

//and SDI pins as serial port pins

SSPCONbits.SSPOV = 0; // no overflow allowed as we are in Master mode

SSPCONbits.WCOL = 0; // no collision

/*****SSPSTATbits*****/

SSPSTATbits.CKE = 1; // data transmitted on rising edge of clock

SSPSTATbits.SMP = 1; // input data sampled at end of output data

PORTCbits.RC6 = 1; // Disable Chip Select

/*****/

}

void send_spi_byte(char addr, char data)

{

SSPBUF = addr; // send 8 bit address MSB first

while (!SSPSTATbits.BF) // wait for 8 bits address data to transmit/ complete

```

```

    {
        ; // do nothing
    }

SSPBUF = data; // send 8 bit data MSB first
while (!SSPSTATbits.BF) // wait for 8 bits data / transmit complete
    {
        ; // do nothing
    }

}

void send_no_op_spi_byte (void)
{

SSPBUF = 0x00; // send 8 bit address MSB first
while (!SSPSTATbits.BF) // wait for 8 bits address data to transmit/ complete
    {
        ; // do nothing
    }

SSPBUF = 0x00; // send 8 bit data MSB first
while (!SSPSTATbits.BF) // wait for 8 bits data / transmit complete
    {
        ; // do nothing
    }

}

/* initialise matrix 1 */

```

```

void init1_max7219()
{
    PORTCbits.RC6 = 0;

    send_spi_byte (normal_operation_addr,normal_operation_data);//leave shutdown mode and enter normal
operation

    PORTCbits.RC6 = 1;

    PORTCbits.RC6 = 0;

    send_spi_byte (display_intensity_addr,display_intensity_data);// minimum display intensity 1/32

    PORTCbits.RC6 = 1;

    PORTCbits.RC6 = 0;

    send_spi_byte (decode_off_addr,decode_off_data); // decode mode off

    PORTCbits.RC6 = 1;

    PORTCbits.RC6 = 0;

    send_spi_byte (scan_limit_addr,scan_limit_data); // scan limit = 8 digits multiplexed

    PORTCbits.RC6 = 1;    // LOAD is high
}

```

/* initialise matrix 2 */

```

void init2_max7219()
{
    PORTCbits.RC6 = 0;

    send_spi_byte (normal_operation_addr,normal_operation_data);//leave shutdown mode and enter normal
operation

    send_no_op_spi_byte();

    PORTCbits.RC6 = 1;

    PORTCbits.RC6 = 0;

```



```

send_spi_byte (display_intensity_addr,display_intensity_data);// minimum display intensity 1/32

send_no_op_spi_byte();

PORTCbits.RC6 = 1;

PORTCbits.RC6 = 0;

send_spi_byte (decode_off_addr,decode_off_data); // decode mode off

send_no_op_spi_byte();

PORTCbits.RC6 = 1;

PORTCbits.RC6 = 0;

send_spi_byte (scan_limit_addr,scan_limit_data); // scan limit = 8 digits multiplexed

send_no_op_spi_byte();

PORTCbits.RC6 = 1;    // LOAD is high
}

/* initialise matrix 3 */
void init3_max7219()
{
    PORTCbits.RC6 = 0;

    send_spi_byte (normal_operation_addr,normal_operation_data);//leave shutdown mode and enter normal
operation

    send_no_op_spi_byte();

    send_no_op_spi_byte();

    PORTCbits.RC6 = 1;

    PORTCbits.RC6 = 0;

    send_spi_byte (display_intensity_addr,display_intensity_data);// minimum display intensity 1/32

    send_no_op_spi_byte();

    send_no_op_spi_byte();

    PORTCbits.RC6 = 1;

```

```

PORTCbits.RC6 = 0;

send_spi_byte (decode_off_addr,decode_off_data); // decode mode off

send_no_op_spi_byte();

send_no_op_spi_byte();

PORTCbits.RC6 = 1;

PORTCbits.RC6 = 0;

send_spi_byte (scan_limit_addr,scan_limit_data); // scan limit = 8 digits multiplexed

send_no_op_spi_byte();

send_no_op_spi_byte();

PORTCbits.RC6 = 1; // LOAD is high
}

/* initialise matrix 4 */
void init4_max7219()
{
    PORTCbits.RC6 = 0;

    send_spi_byte (normal_operation_addr,normal_operation_data);//leave shutdown mode and enter normal
operation

    send_no_op_spi_byte();

    send_no_op_spi_byte();

    send_no_op_spi_byte();

    PORTCbits.RC6 = 1;

PORTCbits.RC6 = 0;

send_spi_byte (display_intensity_addr,display_intensity_data);// minimum display intensity 1/32

send_no_op_spi_byte();

send_no_op_spi_byte();

send_no_op_spi_byte();

```

```
PORTCbits.RC6 = 1;
```

```
PORTCbits.RC6 = 0;
```

```
send_spi_byte (decode_off_addr,decode_off_data); // decode mode off
```

```
send_no_op_spi_byte();
```

```
send_no_op_spi_byte();
```

```
send_no_op_spi_byte();
```

```
PORTCbits.RC6 = 1;
```

```
PORTCbits.RC6 = 0;
```

```
send_spi_byte (scan_limit_addr,scan_limit_data); // scan limit = 8 digits multiplexed
```

```
send_no_op_spi_byte();
```

```
send_no_op_spi_byte();
```

```
send_no_op_spi_byte();
```

```
PORTCbits.RC6 = 1; // LOAD is high
```

```
}
```

```
/* initialise matrix 5 */
```

```
void init5_max7219()
```

```
{
```

```
PORTCbits.RC6 = 0;
```

```
send_spi_byte (normal_operation_addr,normal_operation_data);//leave shutdown mode and enter normal operation
```

```
send_no_op_spi_byte();
```

```
send_no_op_spi_byte();
```

```
send_no_op_spi_byte();
```

```
send_no_op_spi_byte();
```

```
PORTCbits.RC6 = 1;
```

```

PORTCbits.RC6 = 0;

send_spi_byte (display_intensity_addr,display_intensity_data);// minimum display intensity 1/32

send_no_op_spi_byte();

send_no_op_spi_byte();

send_no_op_spi_byte();

send_no_op_spi_byte();

PORTCbits.RC6 = 1;

PORTCbits.RC6 = 0;

send_spi_byte (decode_off_addr,decode_off_data); // decode mode off

send_no_op_spi_byte();

send_no_op_spi_byte();

send_no_op_spi_byte();

send_no_op_spi_byte();

PORTCbits.RC6 = 1;

PORTCbits.RC6 = 0;

send_spi_byte (scan_limit_addr,scan_limit_data); // scan limit = 8 digits multiplexed

send_no_op_spi_byte();

send_no_op_spi_byte();

send_no_op_spi_byte();

send_no_op_spi_byte();

PORTCbits.RC6 = 1; // LOAD is high
}

/*****Function reads the ith ascii character from message string and returns this ascii character */
char get_char (char i )
{
char *char_ptr; // declare a pointer to char which will read characters from message

char_ptr = (void*)&message[i]; // pointer points to the ith element of message

```

```

    return *char_ptr;    // returns the ascii character found at &message[i]
}

/*****
*****/

/*****Function matches ascii character in LUT and returns 8x8
bitmap*****/

char check_null_char(char i)
{
    char n;

    if(get_char(i) == '\0')    // if we run out of characters in message[], clear n
    {
        n = 0;
    }

    return n;
}

void main(void)
{
/*****INITIALISATION OF PORT PINS, SPI REGISTERS & MAX7219 CHIP*****/

    init_ports();           // initialise PORTC pins 8, 9,11
    init_spi();             // initialise SPI registers
    init1_max7219();        // initialise all 5 MAX7219 chips
    init2_max7219();        // individually
    init3_max7219();
    init4_max7219();
    init5_max7219();

/*****

    char *pm5, *pm4, *pm3, *pm2, *pm1; // declare five pointers to point to five

```

```

char matrix_5, matrix_4, matrix_3, matrix_2, matrix_1;// consecutive characters

int cnt;                // in message[]

char x;

pm5 = (void*)&message[0]; // pm5 (pointer matrix 5) points to address of 1st char
pm4 = (void*)&message[8]; // pm4 points to 2nd char in message[]
pm3 = (void*)&message[16]; // pm3 points to 3rd char in message[]
pm2 = (void*)&message[24]; // pm2 points to 2nd char in message[]
pm1 = (void*)&message[32]; // pm1 points to 1st char in message[]

while(1)
{
    for ( cnt = 0; cnt < 392; cnt++) //this loop effectively pulls the message[]
    {
        // left across the five 8x8 matrices to create
        // the scrolling message effect

        for (x = 1; x < 9; x++) // this loop writes the data the pointer points
        {
            // to in the appropriate 8x8 matrix

            matrix_5 = *pm5;

            PORTCbits.RC6 = 0;

            send_spi_byte(x, matrix_5);

            send_no_op_spi_byte();

            send_no_op_spi_byte();

            send_no_op_spi_byte();

            send_no_op_spi_byte();

            PORTCbits.RC6 = 1;

            pm5 = pm5 + 1; // pointer now points to next character to the right

            matrix_4 = *pm4;

            PORTCbits.RC6 = 0;

            send_no_op_spi_byte();

```

```
send_spi_byte(x, matrix_4);  
  
send_no_op_spi_byte();  
  
send_no_op_spi_byte();  
  
send_no_op_spi_byte();  
  
PORTCbits.RC6 = 1;  
  
pm4 = pm4 + 1;
```

```
matrix_3 = *pm3;  
  
PORTCbits.RC6 = 0;  
  
send_no_op_spi_byte();  
  
send_no_op_spi_byte();  
  
send_spi_byte(x, matrix_3);  
  
send_no_op_spi_byte();  
  
send_no_op_spi_byte();  
  
PORTCbits.RC6 = 1;  
  
pm3 = pm3 + 1;
```

```
matrix_2 = *pm2;  
  
PORTCbits.RC6 = 0;  
  
send_no_op_spi_byte();  
  
send_no_op_spi_byte();  
  
send_no_op_spi_byte();  
  
send_spi_byte(x, matrix_2);  
  
send_no_op_spi_byte();  
  
PORTCbits.RC6 = 1;  
  
pm2 = pm2 + 1;
```

```
matrix_1 = *pm1;  
  
PORTCbits.RC6 = 0;
```

```

    send_no_op_spi_byte();

    send_no_op_spi_byte();

    send_no_op_spi_byte();

    send_no_op_spi_byte();

    send_spi_byte(x, matrix_1);

    PORTCbits.RC6 = 1;

    pm1 = pm1 + 1;
}

__delay_ms(40);          // delay sets speed of scrolling

pm5 = (void*)&message[cnt];    // these offsets to the address of each character

pm4 = (void*)&message[cnt + 8]; // allow the scrolling feature

pm3 = (void*)&message[cnt + 16];

pm2 = (void*)&message[cnt + 24];

pm1 = (void*)&message[cnt + 32];

if ((void*)*pm1 == "\0")      // when the pointer pm1 finds the null character
{
    // at the end of message[], it resets all pointer

    pm5 = (void*)&message[0]; // addresses and clears counter variable cnt

    pm4 = (void*)&message[8];

    pm3 = (void*)&message[16];

    pm2 = (void*)&message[24];

    pm1 = (void*)&message[32];

    cnt = 0;
}
}
}
}

```